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Seelig

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(54) **APPARATUS AND METHODS FOR
REDUCTION OF VERTEBRAL BODIES IN A
SPINE**

USPC 606/57, 60, 90, 99, 105, 246–279, 86 A
See application file for complete search history.

(71) Applicant: **Zimmer Spine, Inc.**, Minneapolis, MN
(US)

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(72) Inventor: **Matthew E. Seelig**, Austin, TX (US)

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(73) Assignee: **Zimmer Spine, Inc.**, Minneapolis, MN
(US)

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This patent is subject to a terminal dis-
claimer.

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2008.

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Primary Examiner — Christopher Beccia

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(74) *Attorney, Agent, or Firm* — Seager, Tufte & Wickhem,
LLC

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(63) Continuation of application No. 11/567,889, filed on
Dec. 7, 2006, now Pat. No. 8,679,128.

(57)

ABSTRACT

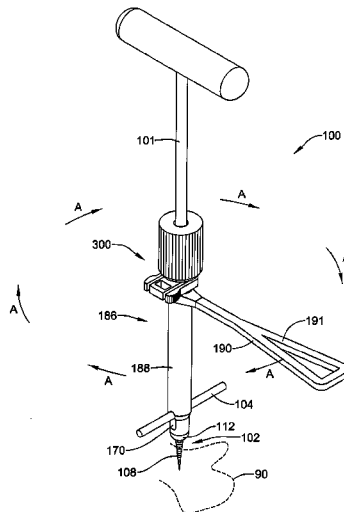
(51) **Int. Cl.**
A61B 17/88 (2006.01)
A61B 17/70 (2006.01)
A61B 19/00 (2006.01)

A system for reduction of vertebral bodies (or vertebrae) in various embodiments includes a reducer, and extender, and a hollow tube. The reducer couples to the extender, which in turn couples to an elongated member, such as a rod, and to a bone fastener assembly. The reducer allows reduction of the vertebral body incrementally, and by a desired amount. The reducer may include or may be used in conjunction with a holding device or holder in order to hold or keep the amount of reduction constant or steady once the desired amount of reduction has been obtained. The reducer may use one of several embodiments, including embodiments that use threaded assemblies or members, inclining members or wedges, offset cams, scissor jacks, and/or levers.

(52) **U.S. Cl.**
CPC **A61B 17/8866** (2013.01); **A61B 17/7086**
(2013.01); **A61B 17/7032** (2013.01); **A61B**
2019/307 (2013.01)

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CPC A61B 17/8866; A61B 17/58; A61B
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20 Claims, 21 Drawing Sheets



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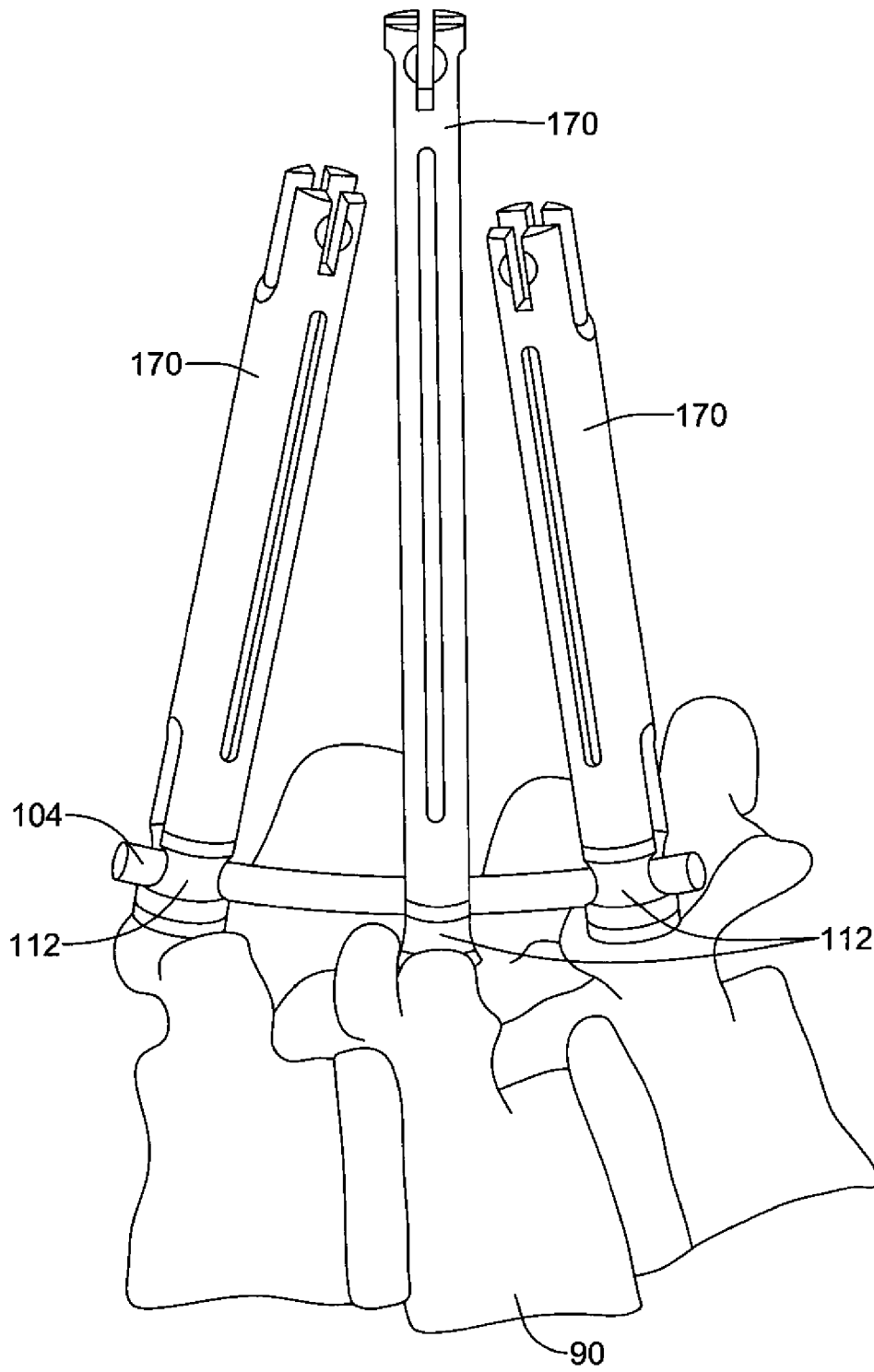


Figure 1A

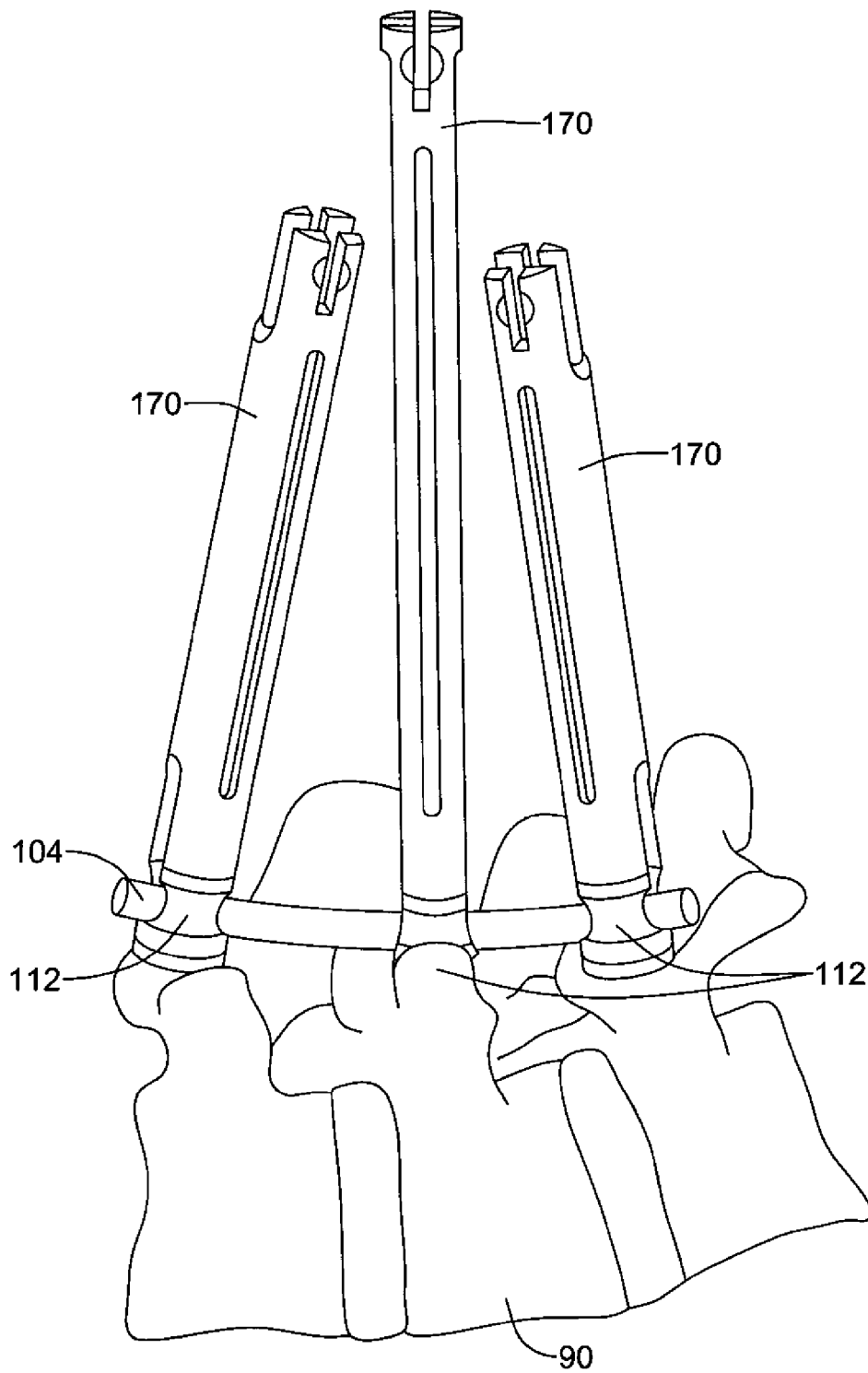


Figure 1B

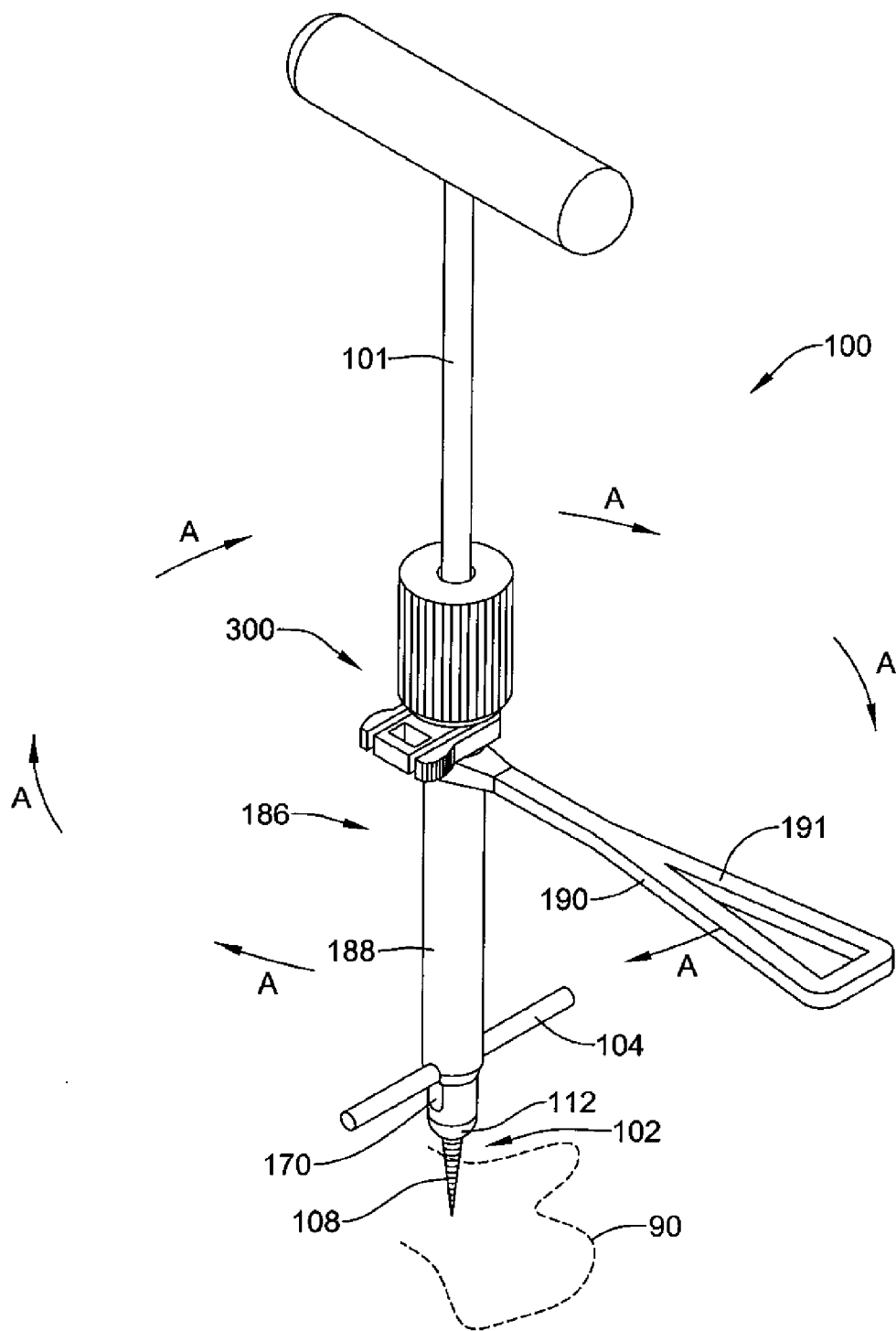


Figure 2A

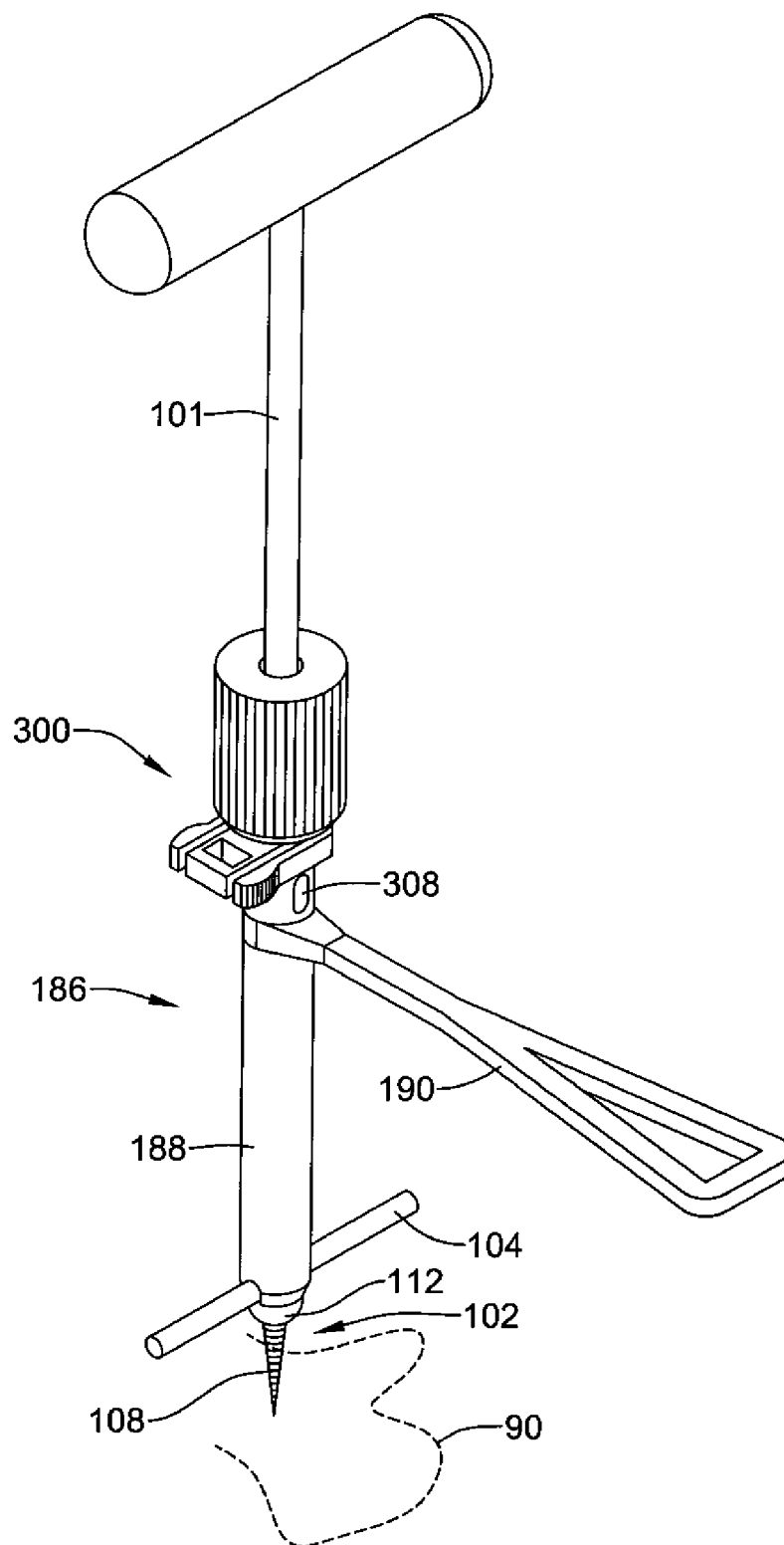


Figure 2B

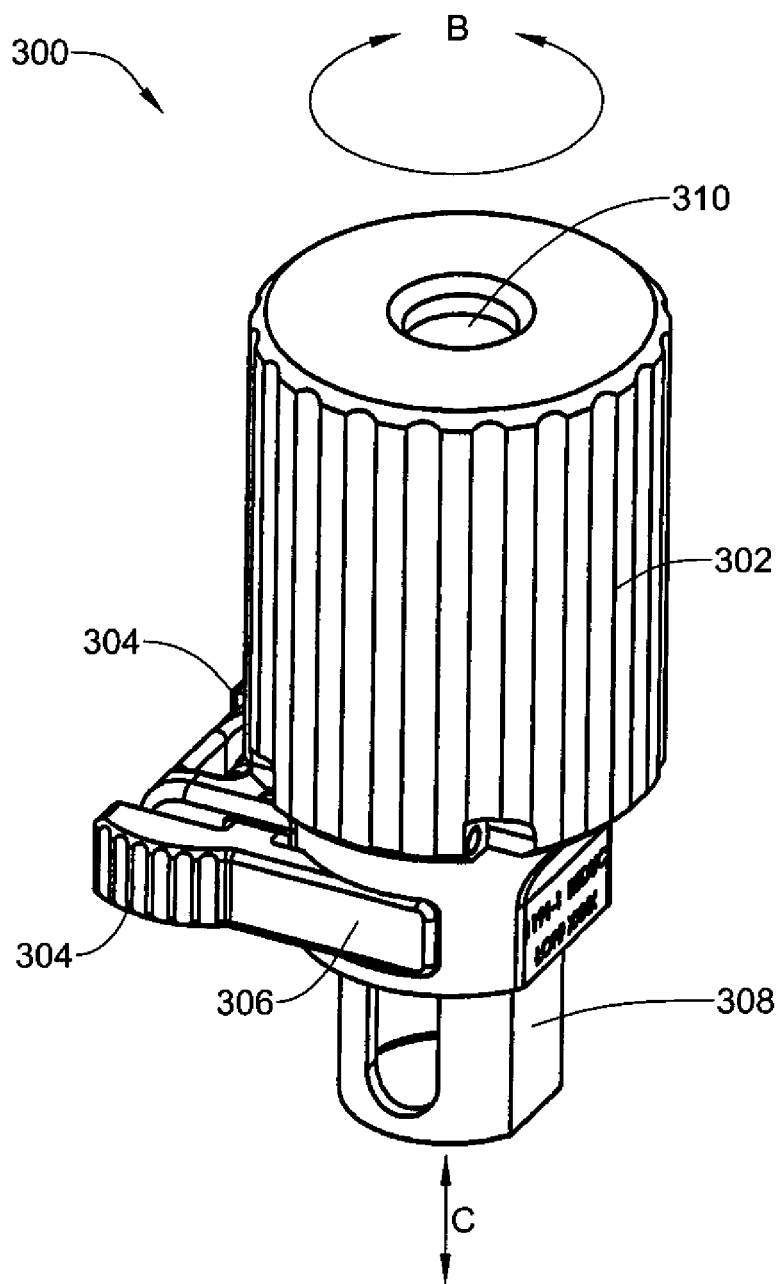


Figure 3

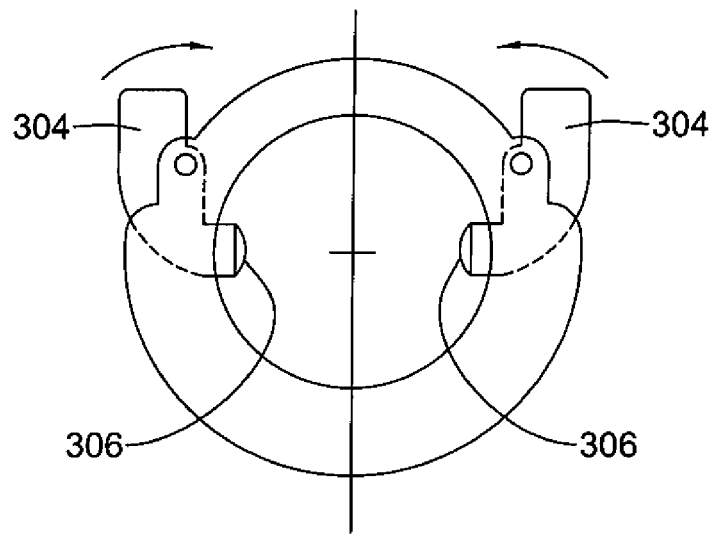


Figure 4

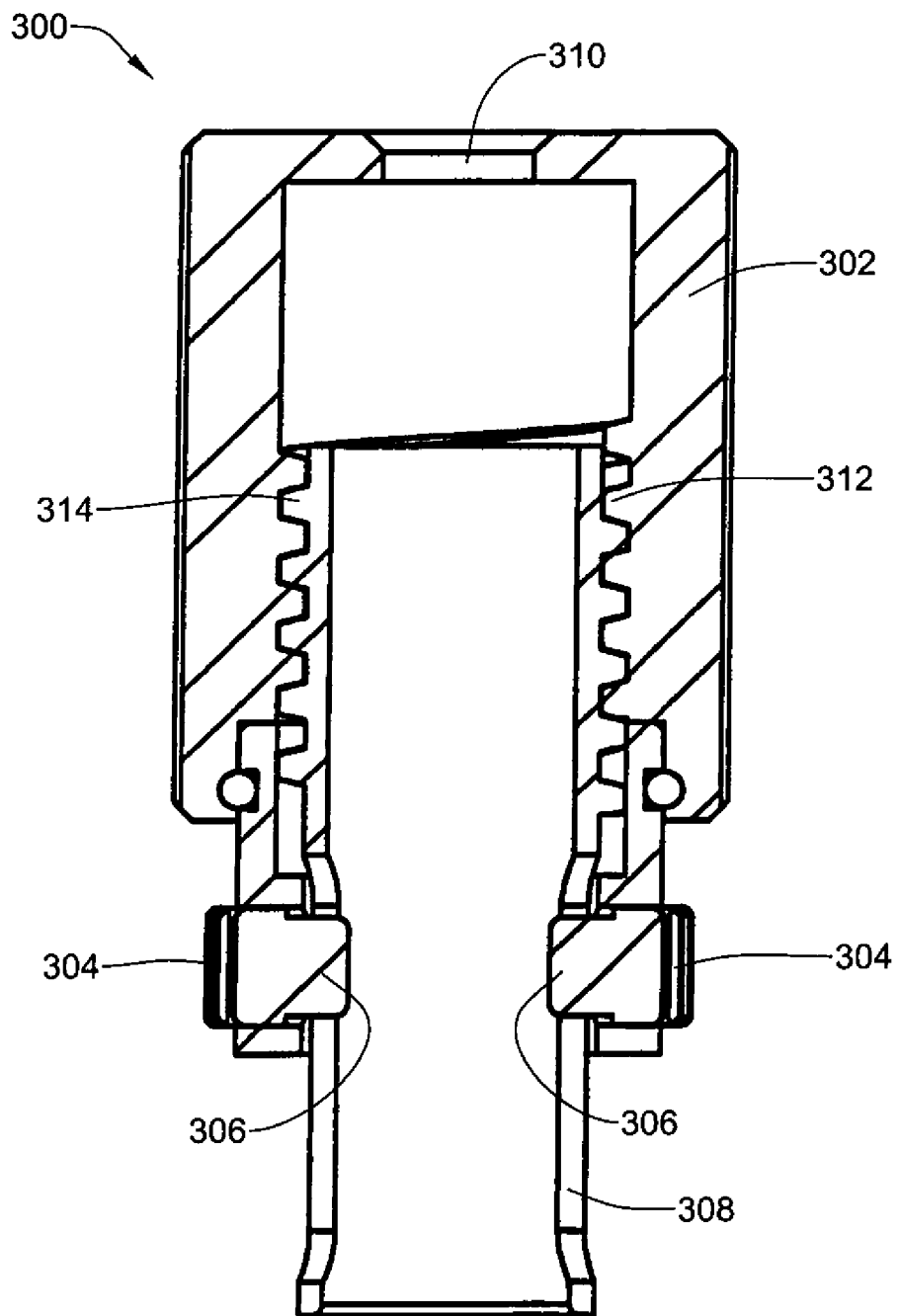


Figure 5

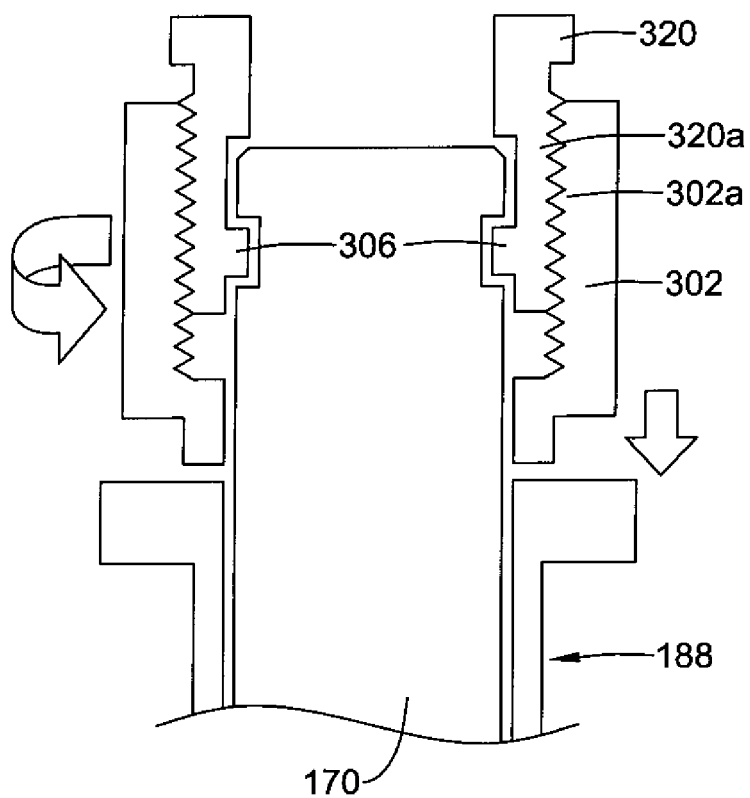


Figure 6

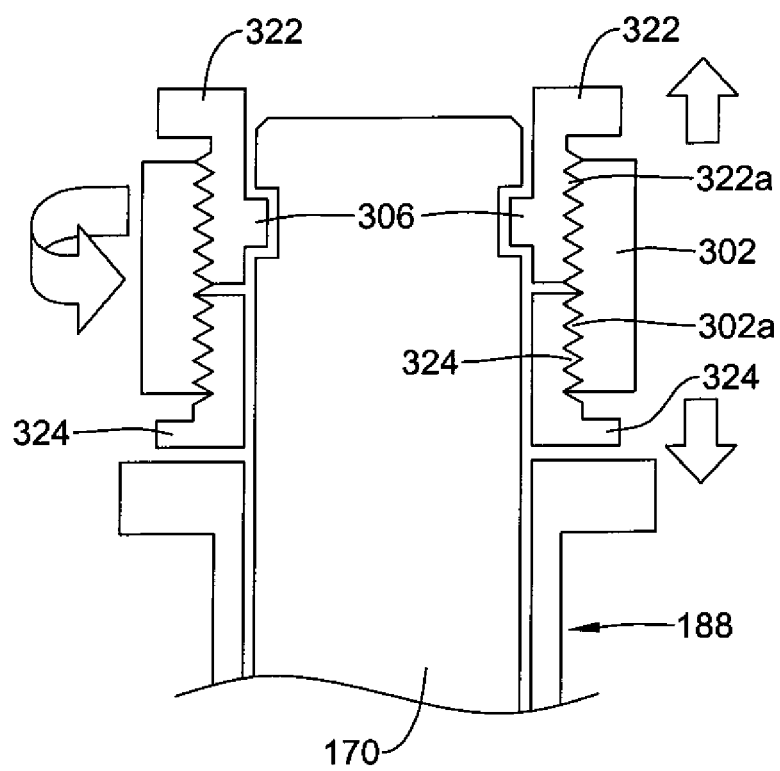


Figure 7

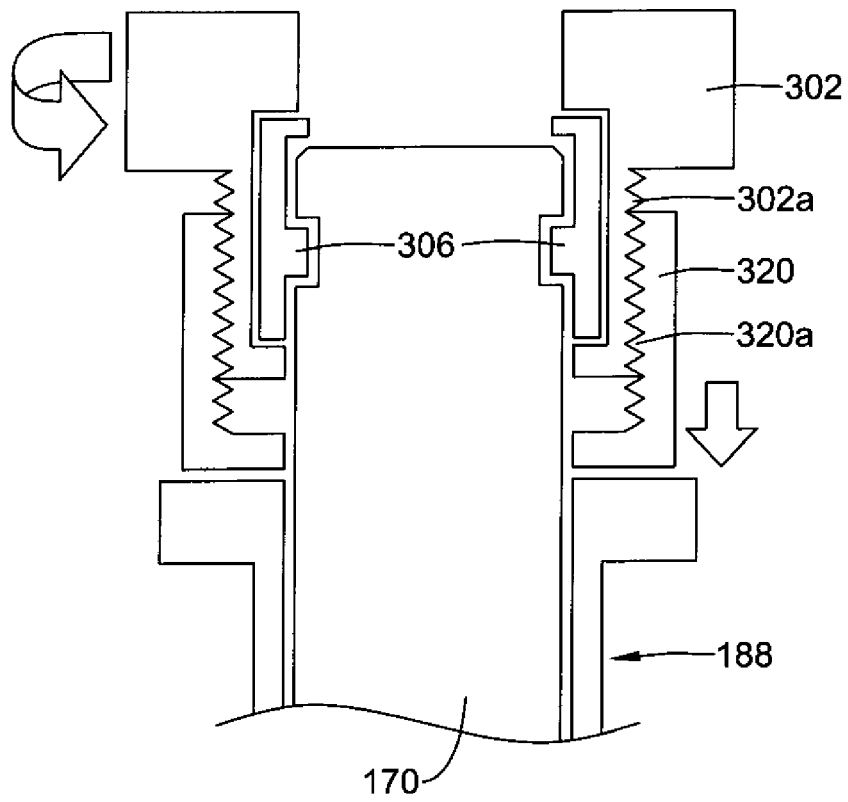


Figure 8

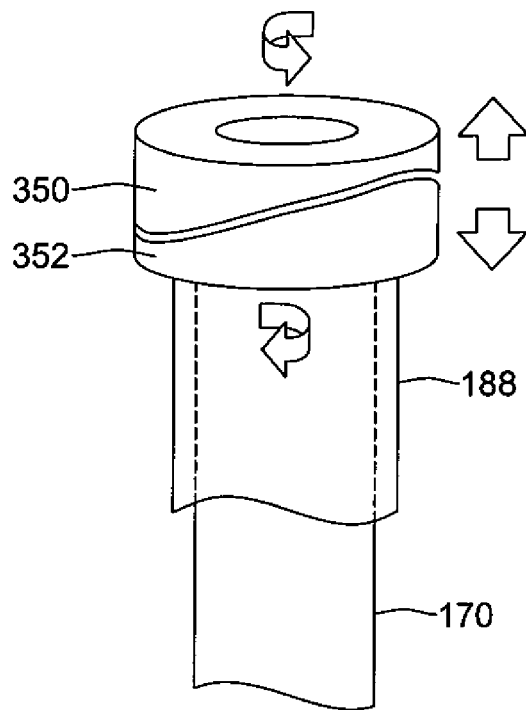


Figure 9

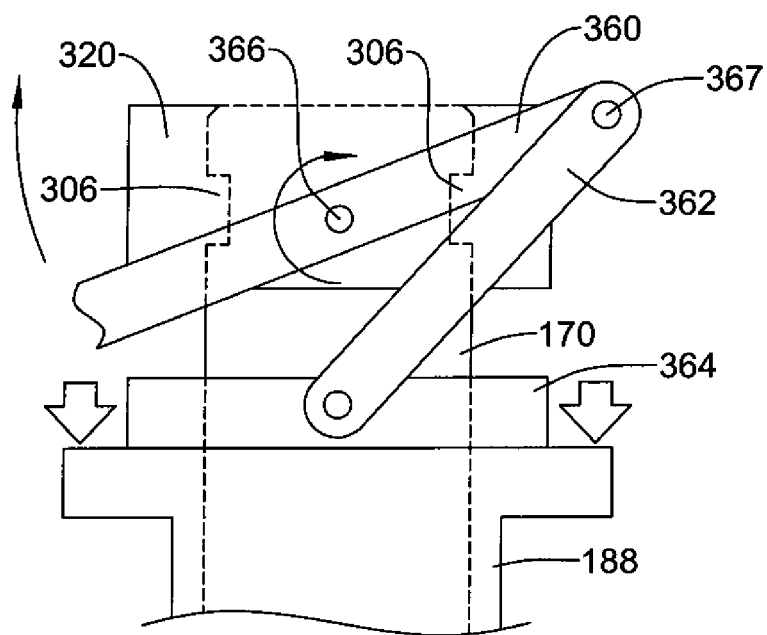


Figure 10

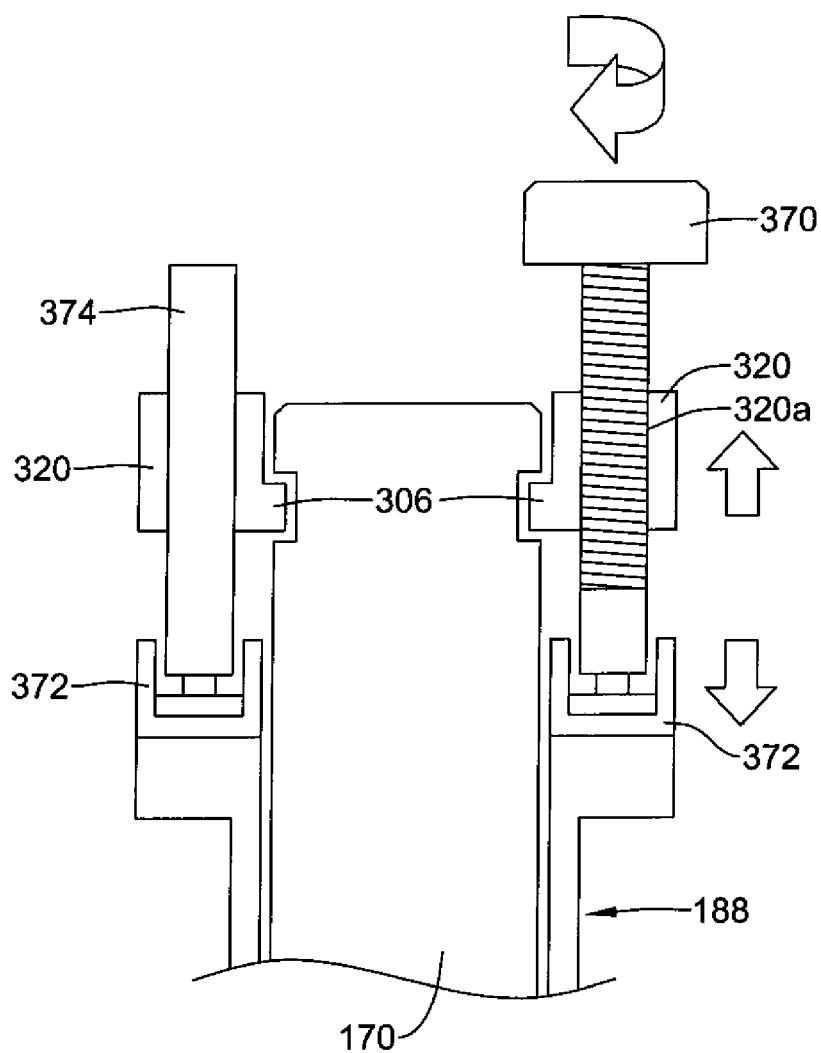


Figure 11

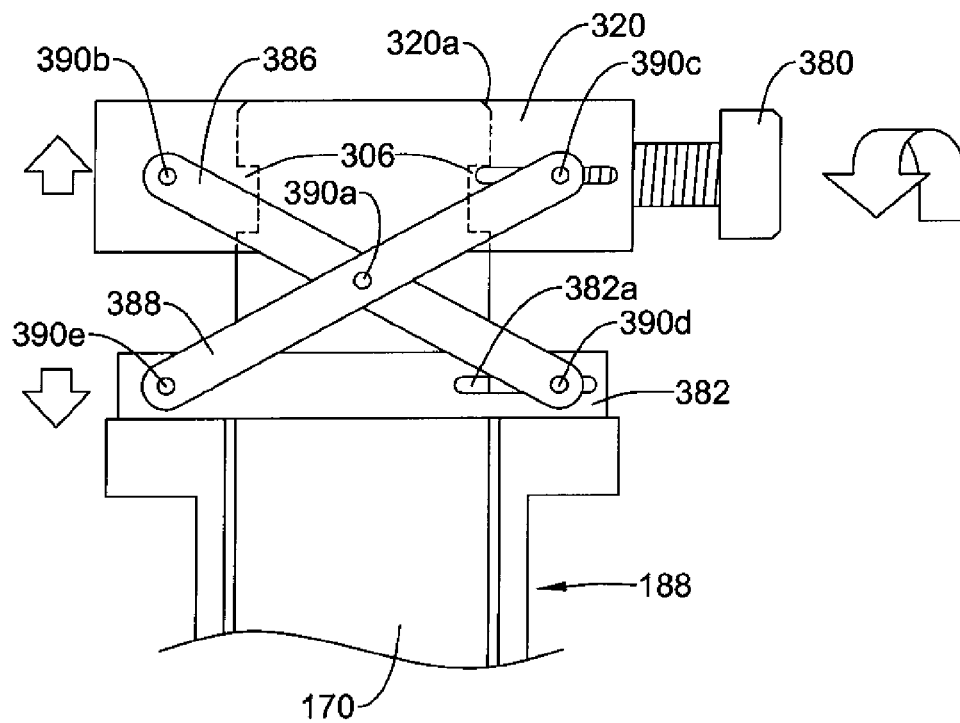


Figure 12

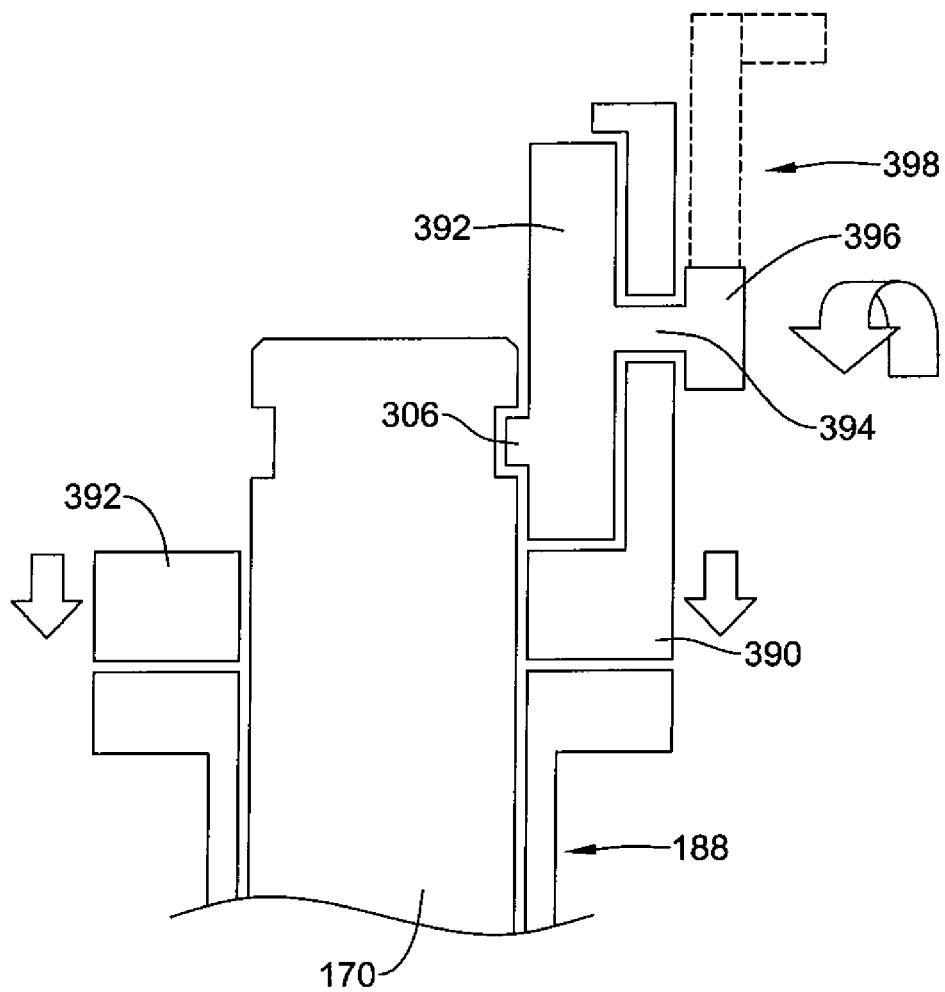


Figure 13

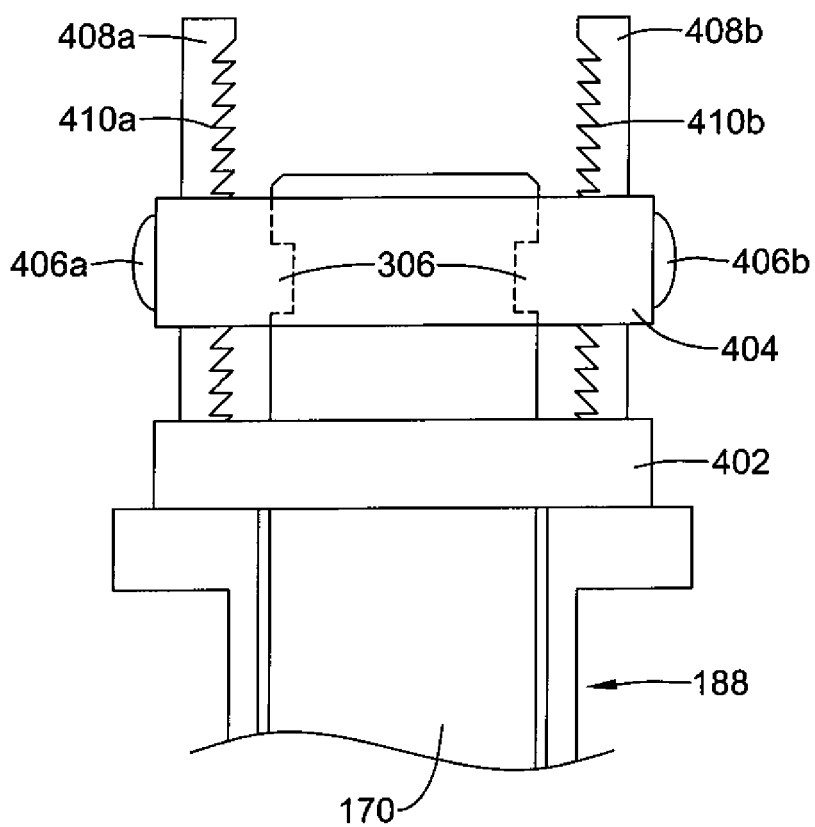
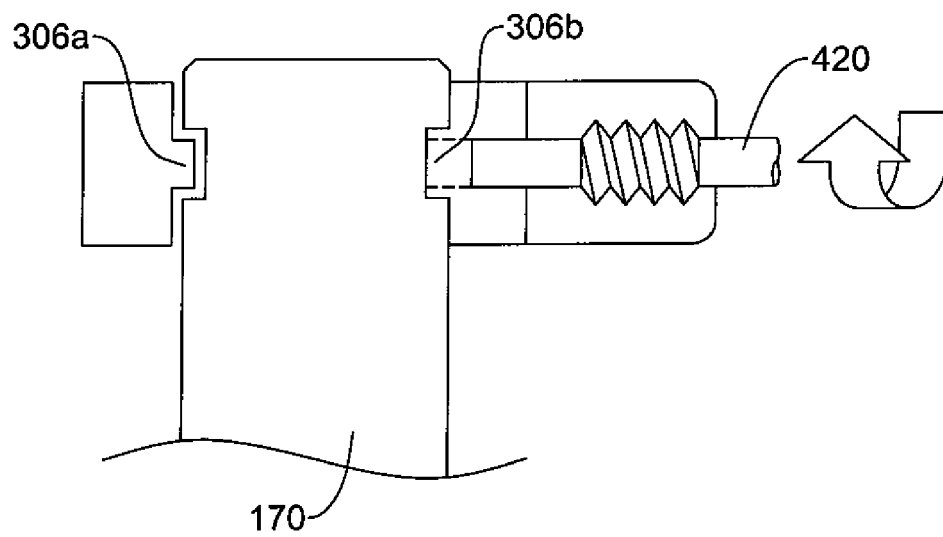


Figure 14

*Figure 15*

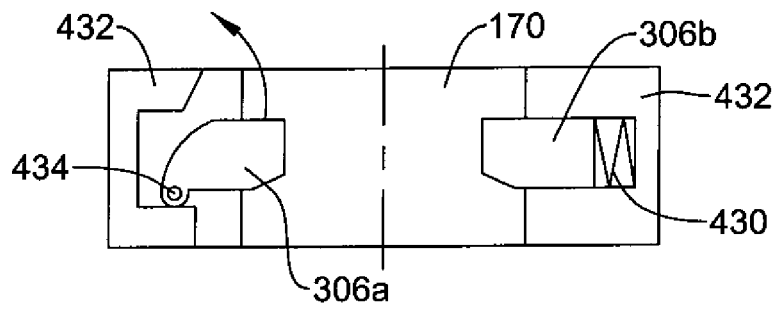


Figure 16

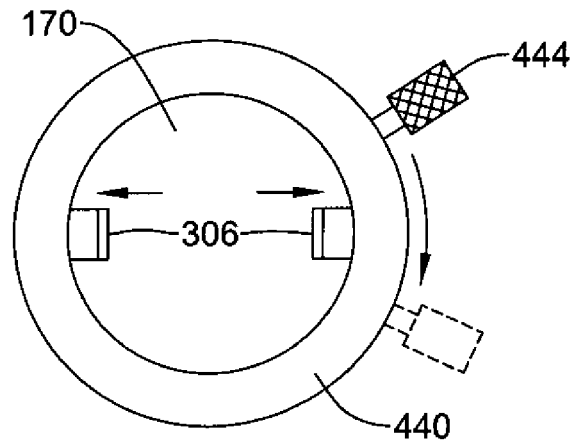


Figure 17

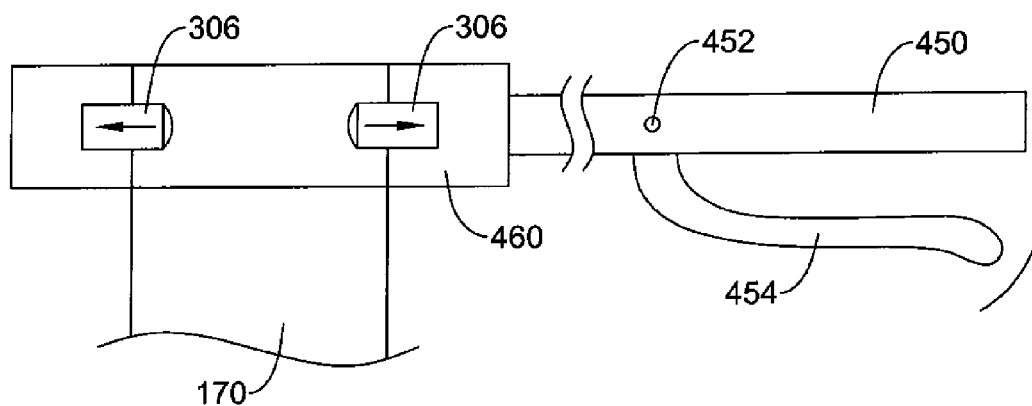


Figure 18

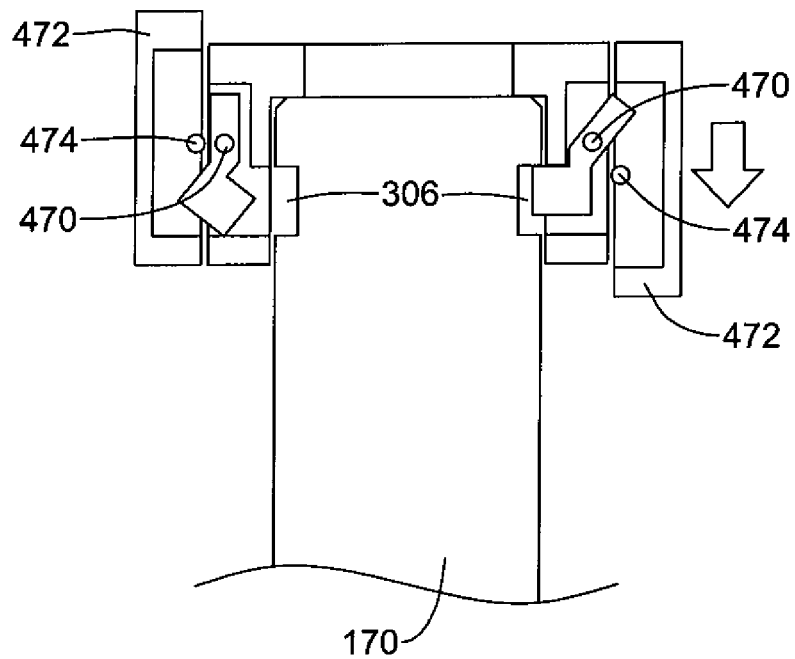


Figure 19

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APPARATUS AND METHODS FOR REDUCTION OF VERTEBRAL BODIES IN A SPINE

CROSS-REFERENCE TO RELATED APPLICATIONS

The present application is a continuation application of U.S. patent application Ser. No. 11/567,889, filed Dec. 7, 2006, the complete disclosure of which is herein incorporated by reference.

TECHNICAL FIELD

The present invention generally relates to apparatus and methods used during a spinal surgical procedure. More particularly, the inventive concepts relate to spinal surgical procedure that use apparatus and methods for reducing vertebral bodies.

BACKGROUND

Modern spine surgery often involves the use of spinal implants to correct or treat various spine disorders or to support the spine. Spinal implants may help, for example, to stabilize the spine, correct deformities of the spine, facilitate fusion, treat spinal fractures, repair annular defects, etc.

Spinal implant systems for a lumbar region of the spine may be inserted during a procedure using a posterior spinal approach. Conventional systems and methods for such operations may involve dissecting and retracting soft tissue near or around the surgical site, which may cause trauma to the soft tissue, and extend recovery time.

Minimally invasive procedures and systems may reduce recovery time as well as trauma to the soft tissue surrounding a stabilization site. During minimally invasive surgical procedures, often a reduction of one of more vertebrae are indicated. A need exists for reduction apparatus and related methods that provide flexibility of operation, enhanced range of reduction, and adaptability to the patient's anatomy.

SUMMARY

The disclosed inventive concepts relate to apparatus and methods for reduction of vertebrae or vertebral bodies. In one exemplary embodiment, an apparatus according to the invention includes a reducer, and an extender coupled releasably to the reducer. The reducer includes a sleeve and a knob. The sleeve has a threaded portion. Similarly, the knob has a threaded portion that is in engagement with the threaded portion of the sleeve to provide reduction of the vertebra or vertebral body.

In another exemplary embodiment, a system for reducing a vertebra or vertebral body includes an extender and a reducer. The reducer is releasably coupled to the extender, and is configured to allow incremental reduction of the vertebral body.

Yet another exemplary embodiment relates to a method of reducing a vertebra or vertebral body. The method includes moving incrementally one member with respect to a second member. The first member is releasably coupled to the vertebra, which results in the reduction of the vertebra or vertebral body.

BRIEF DESCRIPTION OF THE DRAWINGS

The appended drawings illustrate only exemplary embodiments of the invention and therefore should not be considered

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or construed as limiting its scope. Persons of ordinary skill in the art who have the benefit of the description of the invention appreciate that the disclosed inventive concepts lend themselves to other equally effective embodiments. Unless noted otherwise, in the drawings, the same numeral designators used in more than one drawing denote the same, similar, or equivalent functionality, components, or blocks.

FIGS. 1A and 1B show details of how a typical reduction procedure brings into alignment a misaligned vertebra.

FIG. 2A shows a system for a spinal surgical operation that uses a reducer according to an exemplary embodiment of the invention.

FIG. 2B illustrates reduction of a vertebral body by operating the reducer shown in FIG. 2A.

FIG. 3 depicts a reducer according to one exemplary embodiment of the invention.

FIG. 4 shows a top view of the locking handles and locking members of the reducer in FIG. 3.

FIG. 5 illustrates a cross-section of the exemplary reducer illustrated in FIG. 3.

FIGS. 6-13 depict a plurality of reducers according to exemplary embodiments of the invention.

FIG. 14 shows a holding device according to one aspect of the inventive concepts for use with reducers according to the invention.

FIGS. 15-19 illustrate a plurality of attachment mechanisms according to exemplary embodiments of the invention.

DETAILED DESCRIPTION

The disclosed novel concepts relate to apparatus and methods for reducing vertebrae or vertebral bodies during minimally invasive surgical procedures, for example, during a spinal stabilization procedure. Details of minimally invasive surgery are described in detail in U.S. patent application Ser. No. 10/980,675, titled "Instruments and Methods for Reduction of Vertebral Bodies," filed on Nov. 3, 2004, and incorporated by reference in this application. Briefly, minimally invasive surgery uses apparatus such as guide wires, bone fastener assemblies, extenders, and sleeves, as described in detail in U.S. patent application Ser. No. 10/980,675, referenced above.

During minimally invasive surgery, a reduction of one or more vertebral bodies is indicated. As persons of ordinary skill in the art who have the benefit of the description of the invention understand, reduction generally refers to the replacement or realignment of a body part in normal position or restoration of a bodily condition to normal. FIGS. 1A and 1B show details of how a typical reduction procedure brings into alignment a misaligned vertebra.

More specifically, in FIG. 1A, vertebral body **90** is out of alignment with the rest of the spine and is to be returned to its original position via a reduction procedure. To do so, the surgeon constructs a "framework" or assembly that will serve as the alignment point. The surgeon constructs the framework with pedicle screws or other suitable fasteners and a rod or elongated member to bridge the "bad" (defective or diseased) segment or vertebra and anchoring to the two "good" (healthy and properly aligned) adjacent segments or vertebrae above and below.

The surgeon places fasteners or pedicle screws (collar **112** of the fastener assembly is shown explicitly) into the desired vertebral bodies, including the "bad" segment (labeled **90**). Once in place, the surgeon locates an elongated member or rod **104** in the adjacent bone fastener assemblies (e.g., screw heads), and fastens it with a closure mechanism (e.g., closure

cap). The rod is contoured in a manner that will hold the proper alignment of the segments or vertebrae once the reduction procedure is complete.

To aid in the reduction, the surgeon uses one or more extenders. Because elongated member or rod **104** passes through the middle extender (labeled **170**) in the figure, which is in turn attached to the pedicle screw or fastener of the “bad” segment, the extender serves two purposes. First, the extender acts as a guide for the proper alignment of elongated member or rod **104** into the fastener assembly (e.g., screw head).

The extender also serves as a mechanism to “pull up” on the fastener or screw and consequently the vertebral body until elongated member or rod **104** is properly seated within the fastener assembly (e.g., screw head). As described below in more detail, this is done by “pushing” incrementally against elongated member or rod **104** with a hollow shaft or tube (see for example item **188** in FIGS. **2A** and **2B**) while “pulling” up on extender **170** in a manner similar to a tackle being used to hoist up a load.

This incremental, controlled relative motion is achieved by reducer (described below in detail). As detailed below, one part of the reducer is releasably coupled to extender **170** via locking member(s), while another part of the reducer (reduction shaft **308**) is coupled to shaft or tube **188**, which is in turn anchored or coupled to elongated member or rod **104**.

FIG. **1B** shows vertebral body **90** in its reduced state. Note that it is completely or substantially aligned with the rest of the spine or adjacent vertebral bodies. At this stage, a closure mechanism is applied that will secure, fasten, or lock elongated member or rod **104** to the bone fastener assembly (e.g., to the screw head), and therefore fix the position of the “bad” or reduced segment or vertebra **90** with respect to the adjacent segments. Bone graft may be applied to aid fusing the segments together while held in place with elongated member or rod **104** and the bone fastener assemblies.

Conventional reducers have a number of disadvantages, such as relatively limited range of operation, relative lack of adaptability to the patient’s anatomy (e.g., the patient’s lordotic curve), failing to allow for incremental reduction, and involving manual interaction by the surgeon at all times or substantially all times, etc.

As described here in detail, the disclosed reduction apparatus and associated methods overcome those limitations. For example, the disclosed reduction apparatus and related techniques allow incremental reduction without continual surgeon intervention, thus allowing for gradual tissue relaxation, provide relatively extended range of operation or reduction, provide quick-coupling capabilities, and adapt more easily to the patient’s anatomy.

FIG. **2A** shows a system **100** for a spinal surgical operation that uses a reducer according to an exemplary embodiment of the invention. System **100** includes bone fastener assembly **102** (e.g., screw, collar, and closure member (e.g., cap)), elongated member **104** (e.g., a rod), extender **170**, sleeve or assembly **186**, and reducer **300**. Some details of system **100** are provided in U.S. patent application Ser. No. 10/980,675, referenced above.

During minimally invasive surgery, extender **170** allows the surgeon to manipulate bone fastener assembly **102** and to couple fastener **108** to vertebra **90**. A distal end of an extender **170** couples to bone fastener assembly **102** and allows the surgeon to manipulate assembly **102**. In the embodiment shown, extender **170** couples to collar **112** of assembly **102**.

After a bone fastener assembly is coupled to extender **170**, a driver may be coupled to a bone fastener of the bone fastener assembly. The driver may be used to insert the bone fastener into vertebral bone, such as vertebra **90**.

Elongated member **104** allows the surgeon to accomplish a desired goal, for example, stabilize the spine, maintain the natural spacing between vertebrae, etc., as persons of ordinary skill in the art who have the benefit of the description of the invention understand. After bone fastener assemblies are installed and an elongated member is placed in the bone fastener assemblies, closure members may be secured to the bone fastener assemblies.

When a closure member is threaded on a bone fastener assembly, a counter torque wrench may be used to inhibit the application of torque to the spine of the patient. A counter torque wrench may hold an extender that is coupled to a collar. The counter torque wrench allows the application of an appropriate or desired amount of torque, for example, to shear off the tool portion of a closure member.

In some embodiments, a counter torque wrench may inhibit application of torque to a patient during tightening of a closure member and/or during shearing of a tool portion of the closure member by applying a force to an elongated member to counter the force applied to a bone fastener assembly by rotation of the closure member.

The counter torque wrench may take a variety of forms. For example, it may constitute a sleeve that includes hollow shaft or tube **188**. Hollow shaft **188** may be inserted through an opening in the body over extender **170** and advanced toward the patient’s spine.

Handle **190** of sleeve or assembly **186** may have of various shapes or designs, as desired. In some embodiments, a shape of handle **190** may facilitate gripping of sleeve or assembly **186** or hollow tube **188**. Handle **190** may include a cut-out portion to facilitate gripping and/or to reduce the weight of the sleeve. In certain embodiments, a shape of handle **190** may be tapered toward hollow shaft **188** to reduce interference and/or increase visibility of a surgical site.

In the embodiment shown, handle **190** includes lock button or mechanism **191**. During normal operation, lock mechanism **191** locks or holds the position of handle **190** with respect to sleeve or assembly **186** or hollow shaft **188**. By pulling back lock button **191**, the surgeon may “flip” handle **190** around (i.e., move it along the path shown by arrows labeled **A**) in order to reduce interference with the patient’s body and/or increase visibility of the surgical site.

In some embodiments, reducing one or more vertebral bodies to the shape of an elongated member (e.g., a contoured elongated member) or to a desired position may be indicated. Reduction of a vertebral body during a spinal stabilization procedure may include forcing or moving the vertebral body into a position determined by the contour of the elongated member used in the spinal stabilization system or by other indicia.

During a spinal stabilization or implant procedure, a first portion of an elongated member may be seated in a collar of a first bone fastener assembly that is coupled to a first vertebra. A closure member may be coupled to the collar and the elongated member to seat the elongated member fully in the collar and to fix the position of the elongated member relative to the first bone fastener assembly.

A second portion of the elongated member may be positioned adjacent to a collar of a second bone fastener assembly that is coupled to a second vertebra. The position of the second vertebra and/or the shape of the elongated member, however, may inhibit the second portion of the elongated member from being fully seated in the collar of the second bone fastener assembly.

A reducer may be coupled to the elongated member and to the collar of the second bone fastener assembly (e.g., via extender **170**). The reducer may be used to reduce the verte-

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bral body, e.g., fully seat the second portion of the elongated member in the collar of the second bone fastener assembly.

While the reducer holds the second portion of the elongated member seated in the collar of the second bone fastener assembly, driver **101** may be used to secure a closure member (e.g., cap or other suitable item) to the collar to fix the position of the elongated member relative to the collar. Radiological imaging or fluoroscopy may be used to determine when the reducer has fully seated the second portion of the elongated member in the collar of the second bone fastener assembly.

Reducers may be used during a minimally invasive surgical procedure or during procedures where access to an elongated member and working room are restricted. During a minimally invasive procedure or a procedure with limited access and/or limited working room, a reducer may be used to pull an extender coupled to a bone fastener assembly of a spinal implant or stabilization system upward (e.g., away from the spine) to seat the elongated member in a collar of the bone fastener assembly. Movement of a reducer may be achieved by, but is not limited to being achieved by, use of threading, cam action, linkage arms, or a combination thereof, as described below.

In some embodiments, a reducer may be used with one or more other instruments to achieve reduction of a vertebral body coupled to a spinal stabilization system. FIG. 2A depicts an embodiment of reducer **300** that may be used in combination with extender **170** and sleeve or assembly **186**, including hollow shaft **188**.

The reducer may be used to seat elongated member **104** in collar **112** of bone fastener assembly **102** when the bone fastener assembly is coupled to a vertebra. The reducer is designed to couple to extender **170** and pull it upward while pushing elongated member **104** into collar **112**.

Without loss of generality, in one embodiment, reduction of vertebral body **90** is accomplished by moving vertebral body **90** coupled to bone fastener assembly **102** relative to elongated member **104** in such a manner that the elongated member **104** is captured within collar **112** of bone fastener assembly **102**, thus holding vertebral body **90** in desired position. The reduction is accomplished by inducing relative motion of elongated member **104** with respect to collar **112** coupled to vertebral body **90** via assembly **102** or vice versa.

An apparatus for inducing relative motion is reducer **300** with engaging tabs **306** and reduction sleeve **308** that moves with respect to engaging tabs **306**. Engaging tabs **306** are coupled to extender **170**, which in turn is coupled to vertebral body **90** via assembly **102**. Reduction sleeve **308** is coupled to hollow shaft **188**, which in turn is coupled to elongated member **104**. By manipulating reduction sleeve **308** with respect to engaging tabs **306**, shaft **188** moves relative to extender **170**. As a consequent, elongated member **104** moves relative to collar **112** of assembly **102**, which is coupled to vertebral body **90**.

Note that the reduction apparatus uses shaft **188** and the extender **170** in order to “reach” through a small incision into the patient and manipulate elongated member **104** with respect to vertebral body **90**. FIG. 2B shows elongated member **104** seated into collar **112** of assembly **102** as a result of operating reducer **300** (i.e., as a result of the reduction of vertebra or vertebral body **90**, as described below in detail).

FIG. 3 shows a reducer according to one exemplary embodiment of the invention. Reducer **300** includes knob or handle **302**, locking handles **304**, locking or engaging members or tabs **306**, reduction sleeve **308**, and bore **310**.

FIG. 4 shows a top view of locking handles **304** and locking members **306**. Locking handles **304** include or couple to a biasing mechanism, e.g., springs to facilitate engagement of

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locking members **306** to extender **170**. Depressing locking handles **304** causes locking members **306** to withdraw from openings in reduction sleeve **308**. Releasing locking handles **304**, however, causes locking members **306** to return to their original positions in the openings.

FIG. 5 shows a cross-section of reducer **300**. Note that an inner portion or surface of knob **302** includes threads **312**. An outer portion or surface of reduction sleeve **308** includes threads **314**, which are complementary to threads **312** of knob **302**.

Once assembled, the threads of knob **302** engage the threads of reduction sleeve **308**. By rotating knob **302** along the arrows labeled “B,” one may cause the coupled or engaged threads of knob **302** and reduction sleeve **308** to cause sleeve **308** to move up or down or vertically, as the arrow labeled “C” shows. The movement of sleeve **308** may in turn cause the corresponding motion of other apparatus or items coupled to it.

During minimally invasive surgery, reducer **300** couples to other surgical apparatus in order to reduce a vertebral body. For example, in one embodiment, reducer **300** couples to extender **170** (see above) via locking members **306**. More specifically, by depressing locking handles **304**, the surgeon causes locking members **306** to withdraw or move in an outward direction (away from sleeve **308**). The surgeon then couples reducer **300** to extender **170** (e.g., by placing reduction sleeve **308** over or inside extender **170**, as desired) and releases locking handles **304**, as described above.

Once reducer **300** has coupled to extender **170**, the surgeon may turn knob **302** in a desired direction and by a desired amount. As described above, the turning of knob **302** causes shaft **188** moves relative to extender **170**. As noted, extender **170** is coupled to the bone fastener assembly **102** (see FIGS. 2A and 2B). Consequently, elongated member **104** moves relative to collar **112** of assembly **102**, which is coupled to vertebral body **90**, hence causing reduction of vertebral body **90**.

By using relatively fine thread pitches, one may allow the surgeon to fine-tune the reduction of the vertebral bodies, as desired. For example, the surgeon may accomplish the reduction through relatively small or incremental steps. This approach provides the benefit of allowing the affected tissue to relax and helps to reduce trauma.

Furthermore, under normal circumstances, the surgeon need not continually manipulate reducer **300**. Put another way, the surgeon may activate reducer **300** by a desired amount (by turning knob **302** in a desired direction and by a desired amount). Once the surgeon finishes manipulating reducer **300**, it maintains the desired or final reduction.

FIG. 6 shows a cross-section of another reducer according to an exemplary embodiment of the invention, coupled to extender **170** and hollow shaft **188**. The reducer in FIG. 6 includes knob **302** and body **320**. Body **320** couples to extender **170** through any suitable or desired mechanism, such as locking members **306**.

Body **320** has a threaded portion **320A** that engages a complementary threaded portion **302A** of knob **302**. Body **320** couples to extender **170**. Turning knob **302** clockwise or counterclockwise causes body **320** and, hence, extender **170** to move up or down relative to hollow shaft **188**. As a result, by turning knob **302** in a desired direction and by a desired amount, the surgeon can reduce the corresponding vertebral body.

FIG. 7 shows a cross-section of another reducer according to an exemplary embodiment of the invention, coupled to extender **170** and hollow shaft **188**. The reducer includes knob **302**, upper body **322**, and lower body **324**. Upper body

322 couples to extender **170** through any suitable or desired mechanism, such as locking members **306**. (Note that, alternatively, or in addition, lower body **324** may couple to extender **170**, as desired, and as persons of ordinary skill in the art who have the benefit of the description of the invention understand.)

Upper body **322** has a threaded portion **322A** that engages a complementary threaded portion **302A** of knob **302**. Similarly, lower body **324** has a threaded portion **324A** that couples to threaded portion **302A** of knob **302**. Threaded portion **322A** and threaded portion **324A** have opposite thread directions. For example, in the embodiment shown, threaded portion **322A** has right-hand threads, whereas threaded portion **324A** has left-hand threads.

Of course, as persons of ordinary skill in the art who have the benefit of the description of the invention understand, one may use other arrangements of threads. For example, in one embodiment, threaded portion **322A** may have left-hand threads and threaded portion **324A** has right-hand threads.

Turning knob **302** clockwise or counterclockwise causes upper body **322** and lower body **324** to move in opposite directions. As extender **170** couples to upper body **322** (or lower body **324**, as desired), movement of upper body **322** (or lower body **324**) causes extender **170** to move up or down relative to hollow tube **188**. As a result, by turning knob **302** in a desired direction and by a desired amount, the surgeon can reduce the corresponding vertebral body.

FIG. 8 shows a cross-section of another reducer according to an exemplary embodiment of the invention, coupled to extender **170** and hollow shaft **188**. The reducer includes knob **302** and body **320**. Body **320** couples to extender **170** through any suitable or desired mechanism, such as locking members **306**.

Body **320** has a threaded portion **320A** that engages a complementary threaded portion **302A** of knob **302**. Turning knob **302** clockwise or counterclockwise causes knob **302** to move relative to body **320**. Note, however, that turning knob **302** does not change its position relative to extender **170**. As extender **170** couples to knob **302**, movement of knob **302** causes extender **170** to move up or down relative to hollow tube **188**. Thus, by turning knob **302** in a desired direction and by a desired amount, the surgeon can reduce the corresponding vertebral body.

FIG. 9 illustrates a cross-section of another reducer according to an exemplary embodiment of the invention, coupled to extender **170** and hollow shaft **188**. The reducer includes two progressively inclined members or wedges **350** and **352**. Progressively inclined wedge **350** couples to extender **170** (via, for example, coupling members not shown explicitly). Progressively inclined wedge **352** couples to hollow shaft **188**.

By turning progressively inclined wedge **350** in a desired direction and by a desired amount, while holding progressively inclined wedge **352** stationary (or vice-versa), the surgeon can cause movement of extender **172** and hence reduce the corresponding vertebral body. Note that one may use a variety of implementations of the reducer, as persons of ordinary skill in the art who have the benefit of the description of the invention understand. For example, one may use progressively inclined wedges **350** and **352** that include steps (rather than a continuously inclining profile) of desired size or height, as desired. Using stepped wedges would allow incremental reduction in discrete amounts or steps.

FIG. 10 depicts a cross-section of another reducer according to an exemplary embodiment of the invention, coupled to extender **170** and hollow shaft **188**. The reducer includes a “z lever” configuration or assembly. Specifically, the reducer

includes base **364** coupled to hollow shaft **188**, and body **320** coupled to extender **170** (e.g., through locking members **306**), lever bar **360**, and truss **362**.

Lever bar **360** couples at joint **367** to truss **362**. Truss **362** couples to base **364** at joint. Lever bar **360** forms a lever, with a fulcrum at joint **366**. The surgeon may lift lever bar **360**, thus exerting downward force on truss **362** through joint **367**. Truss **362** in turn exerts downward pressure on base **364** and hence on hollow tube **188**. Lifting lever bar **360** also causes the lifting of body **320** and thus extender **170**. Consequently, by lifting lever bar **362** by a desired amount, the surgeon can reduce the corresponding vertebral body.

FIG. 11 shows a cross-section of another reducer according to an exemplary embodiment of the invention, coupled to extender **170** and hollow shaft **188**. The reducer includes base **372** coupled to hollow tube **188**, and body **320** coupled to extender **170**.

The reducer further includes bolt or screw **370**, whose threads engage with threaded portion **320A** of body **320**. An end of screw or bolt **370** couples to base **372**. Slide pin **374** couples a portion of body **320** (opposite or distal end from screw or bolt **370** in the embodiment shown in FIG. 11) to base **372**. Slide pin **374** provides stability to the mechanism and facilitates movement of body **320** with respect to base **372**.

The surgeon may turn screw or bolt **370**, which causes body **320** to move closer to (or farther from, depending on the type of threads of screw or bolt **370** and threaded portion **320A**) base **372**. Because extender **170** couples to body **320**, movement of body **320** causes reduction of the corresponding vertebral body.

FIG. 12 illustrates a cross-section of another reducer according to an exemplary embodiment of the invention, coupled to extender **170** and hollow shaft **188**. The reducer includes a “scissor jack” configuration or assembly. Specifically, the reducer includes base **382** coupled to hollow shaft **188**, and body **320** coupled to extender **170** (e.g., through locking members **306**), lever bar **386**, screw or bolt **380**, and lever bar **388**.

Lever bar **386** and lever bar **388** couple to each other at joint **390A**. Lever bar **386** couples to body **320** at joint **390B** and to base **382** at joint **390D**. Similarly, lever bar **388** couples to body **320** at joint **390C** and to body **382** at joint **390E**. By turning screw or bolt **380**, the surgeon causes the location of joint **390C** to move through slot **320A** and the location of joint **390D** to move through slot **382A**, thus lifting body **320** with respect to base **380**.

As noted, body **320** and base **380** couple, respectively, to extender **170** and to hollow shaft **188**. Thus, the lifting of body **320** causes the lifting of extender **170** and therefore reduction of the corresponding vertebral body.

FIG. 13 shows a cross-section of another reducer according to an exemplary embodiment of the invention, coupled to extender **170** and hollow shaft **188**. Generally speaking, the reducer includes an offset cam (locking member **306**) assembly.

The reducer includes body **390** coupled to hollow shaft **188** and disk **392** coupled to extender **170**. Disk **392** couples to one end of shaft **394**, which passes through a bore or opening in body **390**. Another end of shaft **394** couples to handle or member **396**. Note that, rather than separate pieces (e.g., disk **392**, shaft **394**, and member **396**), one may integrate or combine one or more of the components shown in FIG. 13. As merely one example, one may combine shaft **396** and disk **392** as one component.

Crank or handle **398** couples to member **396** and assists in turning shaft **394** and, hence, disk **392**. Disk **392** couples to

extender 170 via locking member 306 (e.g., a cam). Locking member 306 has an offset location with respect to shaft 394. Thus, turning shaft 394 causes the lifting of extender 170 and, hence, the reduction of the corresponding vertebral body.

Another aspect of the invention relates to holding devices suitable for use with reducers according to various embodiments of the invention. FIG. 14 shows a cross section of an exemplary embodiment of a holding device. One may use the holder in conjunction or in combination with a reducer (e.g., the reducers in FIGS. 9, 10, and 13) in order to hold extender 170 in place (i.e., keep steady or hold constant the degree or amount of reduction).

The holder includes base 402 coupled to hollow shaft 188 and body 404 coupled to extender 170. Columns or bars 408A and 408B coupled body 404 to base 402. Body 404 may move along the length of columns 408A and 408B. Columns 408A and 408B have ratcheting teeth 410A and 410B, respectively. Ratcheting teeth 410A and 410B allow upward movement of body 404, but prevent its downward movement. Thus, the holder allows the surgeon to maintain a desired degree or amount of reduction once it is achieved.

The holder further includes release handles or members 406A and 406B. By activating or operating release handles 406A and 406B, the surgeon can cause the release of the ratcheting teeth 410A and 410B, respectively, thus allowing movement of body 404 with respect to base 402.

One may use a variety of mechanisms to couple the reducers according to the invention with extender 170, as persons of ordinary skill in the art who have the benefit of the description of the invention understand. As one specific case, one may couple the reducer to the extender in a releasable manner, such that the surgeon need not reverse some of the reduction procedure steps in order to decouple or release the reducer from the extender. The following description provides some examples of releasable coupling mechanisms that may be used with the reduction apparatus described above.

FIG. 15 shows a cross-section of an attachment mechanism according to an exemplary embodiment of the invention. The attachment mechanism includes locking members 306A and 306B, and screw or bolt 420. Locking members 306A and 306B couple to extender 170, for example, through notches or other mechanisms in extender 170. Locking member 306A is stationary (e.g., part of the body of a reducer), but locking member 306B may move in response to force applied to it.

More specifically, by turning screw or bolt 420, one may cause it to contact and exert force against locking member 306B. Force applied against locking member 306B causes it to engage extender 170 and couple to it. Thus, by using the attachment mechanism, one may securely couple the reducer or other desired apparatus to extender 170 in order to perform the reduction procedure.

FIG. 16 shows a cross-section of other attachment mechanisms according to an exemplary embodiment of the invention. The apparatus shown in FIG. 16 illustrates two locking mechanisms. The locking mechanisms may be included within housing or member 432, for example, the body of a reducer.

One locking mechanism includes locking member 306A. Locking member 306A couples to housing 432 via a joint or hinge 434. Hinge 434 allows locking member 306A to swing or flip down. In this position, locking member 306A engages and couples to extender 170. Hinge 434 also allows locking member 306A to swing or flip up. In this position, locking member 306A disengages or uncouples from extender 170.

The second locking mechanism in FIG. 16 includes locking member 306B and biasing member or spring 430. Locking member 306B may slide within housing 432. When it

slides towards extender 170, locking member 306B engages and couples to extender 170. Conversely, when it slides away from extender 170, locking member 306B disengages and uncouples from extender 170.

Spring 430 exerts some force against locking member 306B, which causes it to slide towards and couple to extender 170. When one desires to uncouple extender 170 from locking member 306B, one may slide away or push back locking member 306B from extender 170.

FIG. 17 depicts a cross-section of an attachment mechanism according to an exemplary embodiment of the invention. The attachment mechanism in FIG. 17 constitutes an "iris type" of mechanism, and includes locking members 306, ring 440, and handle or lever 444.

Turning handle 444 causes movement of locking members 306. More specifically, turning handle 444 in one direction (e.g., clockwise) causes locking members 306 to move towards each other, and thus engage and couple to extender 170. Turning handle 444 in the opposite direction (e.g., counterclockwise), however, causes locking members 306 to move away from each other, and thus disengage and uncouple from extender 170.

FIG. 18 depicts a cross-section of an attachment mechanism according to an exemplary embodiment of the invention. The attachment mechanism in FIG. 18 includes locking members 306, housing 460 (e.g., body or other part of a reducer), shaft 450, and handle 454.

Handle 454 couples to shaft 450 via hinge or joint 452. Engaging handle 454, e.g., by pulling it towards shaft 450, causes locking members 306 to move in one direction, for example, towards each other. As a result, locking members 306 engage with and couple to extender 170.

Disengaging handle 454, e.g., by pulling it away from shaft 450, causes locking members 306 to move in the opposite direction, for example, away each other. As a result, locking members 306 disengage and uncouple from extender 170.

Note that one may include in the apparatus shown in FIG. 18 mechanisms for holding handle 454 in a desired position, as desired, and as persons of ordinary skill in the art who have the benefit of the description of the invention understand. Examples of such mechanisms include ratchets, holding clamps, etc.

FIG. 19 depicts a cross-section of an attachment mechanism according to an exemplary embodiment of the invention. The attachment mechanism in FIG. 19 constitutes a "collet type" includes locking members 306, sleeves 472, and engaging members 474. FIG. 19 shows one attachment mechanism in the locked position (the right side of FIG. 19), and another attachment mechanism in the unlocked position (left side of FIG. 19).

Each of locking members 306 may move around a respective joint or hinge 474. Generally, moving sleeves 472 causes engaging members 472 to contact locking members 306, form a collar or collet around them, and cause them to move. Movement of locking members 306 may cause them to engage and couple to extender 170, or to disengage and uncouple from extender 170. Note that the apparatus in FIG. 19 allows the surgeon to couple either side of the reducer to extender 170 independently of the other side.

As described, several embodiments of reducers according to the inventive concepts use threaded mechanisms or portions. By using a desired thread type and/or pitch, one may provide reducers with desired characteristics, as persons of ordinary skill in the art who have the benefit of the description of the invention understand.

For example, by using a relatively fine thread pitch, one may produce a reducer that causes a relatively small amount

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of reduction for a given amount of activation of the reducer (e.g., turning knob **302** in FIG. 3), and vice-versa. As noted, by using relatively fine thread pitches, one may allow the surgeon to fine-tune the reduction of the vertebral bodies with a relatively high degree of precision.

Furthermore, by varying the size or length of the threaded portion, one may produce reducers with desired characteristics. For example, a relatively long or large threaded portion would allow a relatively large reduction of the vertebral body, and vice-versa. This property allows reducers according to the inventive concepts to overcome the limited range of conventional reducers.

Various modifications and alternative embodiments of the invention in addition to those described here will be apparent to persons of ordinary skill in the art who have the benefit of the description of the invention. Accordingly, the manner of carrying out the invention as shown and described are to be construed as illustrative only.

Persons skilled in the art may make various changes in the shape, size, number, and/or arrangement of parts without departing from the scope of the invention described in this document. For example, persons skilled in the art may substitute equivalent elements for the elements illustrated and described here, or use certain features of the invention independently of the use of other features, without departing from the scope of the invention.

What is claimed is:

1. A spinal reduction apparatus, comprising:
 - a fastener configured to be coupled to a vertebral body;
 - a collar configured to be coupled to the fastener, the collar including a slot for seating an elongated member;
 - a guide having a proximal end and a distal end, the distal end configured to detachably couple directly to the collar; and
 - a reducer configured to be placed over the guide to seat the elongated member in the slot, the reducer comprising:
 - an outer element having a threaded portion;
 - an inner element having a threaded portion in engagement with the threaded portion of the outer element; and
 - first and second tabs coupled to the inner element configured to selectively couple the reducer to the guide, wherein the first and second tabs are configured to fit within a recess in the proximal end of the guide, wherein the first and second tabs are actuatable to disengage from the guide.
2. The apparatus of claim 1, wherein the threaded portion of the outer element is on an interior surface of the outer element and the threaded portion of the inner element is on an exterior surface of the inner element.
3. The apparatus of claim 1, wherein the first and second tabs are biased to engage the guide.
4. The system of claim 3, wherein the first and second tabs are biased by a spring.
5. The apparatus of claim 1, wherein turning one of the outer element or the inner element causes the outer and inner elements to move relative to each other in opposite directions.
6. A system for reducing a vertebral body, comprising:
 - a guide having a proximal end and a distal end, the distal end configured to be coupled to the vertebral body; and
 - a reducer releasably coupled to the proximal end of the guide, the reducer configured to allow incremental reduction of the vertebral body, the reducer comprising:
 - a locking element including one or more elongated tabs configured to selectively engage a recess in the proximal end of the guide; and

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a biasing member configured to bias the elongated tab into engagement with the guide, wherein the locking element is configured to disengage the elongated tab from the guide when the bias of the biasing member is overcome by depressing a first end of the elongated tab.

7. The system of claim 6, wherein the elongated tab has a second end including a connection member configured to be received within the recess in the proximal end of the guide.

8. The system of claim 7, wherein the elongated tab has a pivot point, wherein depressing the first end causes the connection member to be withdrawn from the recess.

9. The system of claim 8, wherein the biasing member includes a spring.

10. The system of claim 9, wherein the locking element includes first and second elongated tabs coupled to opposite sides of the reducer.

11. The system of claim 6, further comprising a hollow shaft that surrounds at least a part of the guide.

12. The system of claim 6, further comprising a bone fastener assembly coupled to the guide and configured to be coupled to the vertebral body.

13. The system of claim 12, further comprising an elongated member configured to couple to the bone fastener assembly when the vertebral body is reduced.

14. The system of claim 6, wherein the reducer further comprises a first threaded member and a second threaded member.

15. The system of claim 14, wherein the vertebral body is reduced by adjusting a position of the first threaded member with respect to a position of the second threaded member.

16. A spinal reduction apparatus comprising:

- a fastener configured to be coupled to a vertebral body;
- a collar configured to be coupled to the fastener, the collar including a slot for seating an elongated member;
- a guide having a proximal end and a distal end, the distal end configured to detachably couple to the collar; and
- a reducer configured to be placed over the guide to seat the elongated member in the slot, the reducer comprising:
 - a sleeve having a threaded portion, the sleeve configured to slide over the guide;
 - a reduction knob having a threaded portion in engagement with the threaded portion of the sleeve; and
 - a locking element coupled to the knob and configured to selectively engage the guide, wherein the locking element includes an elongated tab and the locking element is configured to disengage the guide when a first end of the elongated tab is depressed;

wherein the sleeve includes a first opening and the locking element engages the guide through the first opening of the sleeve.

17. The apparatus of claim 16, wherein the locking element includes first and second elongated tabs biased into engagement with the guide.

18. The apparatus of claim 17, wherein the first and second elongated tabs each have a second end including a connection member configured to be received within a recess in the proximal end of the guide.

19. The apparatus of claim 18, wherein the first and second elongated tabs each have a pivot point, wherein depressing the first ends of the first and second elongated tabs causes the connection members to be withdrawn from the recess.

20. The apparatus of claim 19, wherein the first and second elongated tabs are biased by springs.